## Hybrid Atomistic-Continuum Methods for Dense Liquids

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## **Molecular systems**

- **gases**: intermolecular distances are large in comparison with molecular sizes the intermolecular interactions are negligible
- hard condensed matter: strong intermolecular interactions, long-range orientational and positional order
- **P** molecular liquids and soft matter: energy-entropy interplay. The free-energy scale:  $k_BT$ . The relevant properties of the system are determined by the interplay of the various temporal and spatial scales involved.



## **Multiscale modeling**



Praprotnik, Delle Site, Kremer, Annu. Rev. Phys. Chem. 59, 545 (2008).

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# **Modeling of dense fluids**

#### All-Atom MD simulation:

- allows to study processes at the atomic level of detail
- is often incapable to bridge a gap between a wide range of length and time scales involved in molecular systems

#### Continuum fluid dynamics (CFD):

- allows to model fluid flows on length scales that are out of scope of MD simulation.
- at lower scales (a few molecular diameters) no-slip boundary condition breaks down and surface to volume effects overcome the inertial effects.

#### **Combining the best from both approaches:**

Hybrid Atomistic-Continuum Methods

#### **Multiscale flow**



Kotsalis, Walther, Ding, Praprotnik, Koumoutsakos, submitted.



# **Molecular Dynamics (MD) simulation**

![](_page_5_Figure_1.jpeg)

![](_page_5_Picture_2.jpeg)

#### **Navier-Stokes equation**

**Conservation of momentum:** 

$$\rho(\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u}) = -\nabla p + \nabla \cdot \mathbf{\Pi} + \mathbf{f}$$

Stress tensor:

$$\mathbf{\Pi} = -\eta [\nabla \mathbf{u}]^S - \xi \nabla \cdot \mathbf{u} \mathbf{I}$$

We consider a Newtonian fluid with dynamic viscosity  $\eta$  and bulk viscosity  $\xi$ . The traceless symmetric tensor is defined as  $A_{\alpha\beta}^S = (A_{\alpha\beta} + A_{\beta\alpha}) - (2/3)A_{\gamma\gamma}$ . Conservation of mass:

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{u}) = 0$$

# **Coupling MD and continuum**

- Physical quantities, i.e., density, momentum, energy, and corresponding fluxes must be continuous across the interface.
- Atomistic and continuum domains provide each other with boundary conditions.
- To impose boundary conditions from the MD to continuum domain is relatively easy since it involves temporal and spatial averaging.
- Imposing the continuum boundary conditions on the particle domain presents the major challenge in hybrid methods.

## Hybrid atomistic-continuum schemes

- state variable (Dirichlet) schemes
  - constraint dynamics: closed systems, unsteady flows
  - Schwartz alternating method: steady state, closed systems, good signal-to-noise ratio, iterations required
- flux-exchange schemes: open systems, grand canonical ensemble, fluctuating hydrodynamics, unsteady flows, no iterations required
- S. T. O'Connell, P. A. Thompson, Phys. Rev. E 52, R5792 (1995)
- N. G. Hadjiconstantinou, A. T. Patera, Int. J. Mod. Phys. 8, 967 (1997)
- T. Werder, J. H. Walther, P. Koumoutsakos, J. Comp. Phys. 205,373 (2005)
- E. G. Flekkoy, G. Wagner, J. Feder, Europhys. Lett. 52, 271 (2000)
- G. De Fabritiis, R. Delgado Buscalioni, P. Coveney, Phys. Rev. Lett 97, 134501 (2006).
- R. Delgado Buscalioni, K. Kremer, M. Praprotnik, J. Chem. Phys. 128, 114110 (2008)

# **Continuum fluid dynamics**

• Conservation law for any conserved fluid variable  $\phi(\mathbf{r}, t)$ :

$$\partial \phi / \partial t = -\nabla \cdot \mathbf{J}^{\phi}$$

 $\mathbf{J}^{\phi}(\mathbf{r},t)$  is the associated local flux.

$$oldsymbol{s}$$
 mass:  $\phi=
ho$ ,  $\mathbf{J}^{\phi}=
ho\mathbf{u}$ 

• momentum: 
$$\phi = 
ho \mathbf{u}$$
,  $\mathbf{J}^{\phi} = \mathbf{J}_p = p \, \mathbf{I} + 
ho \mathbf{u} \mathbf{u} + \mathbf{\Pi}$ 

• energy:  $\phi = \rho \epsilon$ ,  $\mathbf{J}^{\phi} = \rho \epsilon \mathbf{u} + \mathbf{J}_p \cdot \mathbf{u} + q$ 

- Constitutive relations:
  - Equation of state:  $p = p(\rho)$
  - Caloric equation of state:  $\epsilon = \epsilon(\rho, T)$
  - Stress tensor:  $\Pi = -\eta [\nabla \mathbf{u}]^S \xi \nabla \cdot \mathbf{u} \mathbf{I}$
  - Conduction heat flux:  $q = -k_c \nabla T$

#### **Finite Volume Method**

$$\int_{V_C} \partial \phi / \partial t \, dV = - \int_{V_C} \nabla \cdot \mathbf{J}^{\phi} \, dV = - \oint_S \mathbf{J}^{\phi} \cdot dS$$
$$\frac{d\Phi_C}{dt} = -\sum_{f=faces} A_f \mathbf{J}_f^{\phi} \cdot \mathbf{n}_f$$

 $\Phi_C = \int_{V_C} \phi(\mathbf{r}, t) d\mathbf{r}^3$ . The above eq. is numerically solved by the explicit Euler scheme, where  $\mathbf{J}_f^{\phi} = (\mathbf{J}_C^{\phi} + \mathbf{J}_{C+1}^{\phi})/2$ .

![](_page_10_Figure_3.jpeg)

R. Delgado Buscalioni, K. Kremer, MP, J. Chem. Phys. 128, 114110 (2008).

TUD Autumn School 2009, Darmstadt, September 24-25, 2009 - p. 11/27

#### **Boundary conditions: MD->CFD**

Mass flux:

$$\frac{1}{V}\sum_{i}m_{i} < \mathbf{v}_{i} > \cdot \mathbf{n} \longrightarrow \rho \mathbf{u} \cdot \mathbf{n}$$

Momentum flux:

$$\frac{1}{V}\sum_{i}\left(m_{i} < \mathbf{v}_{i}\mathbf{v}_{i} > +\frac{1}{2}\sum_{j\neq i} < \mathbf{F}_{ij}\mathbf{r}_{ij} > \right) \cdot \mathbf{n} \longrightarrow \mathbf{J}_{p} \cdot \mathbf{n}$$

Energy flux:

$$\frac{1}{V} < \sum_{i} m_{i} \epsilon_{i} \mathbf{v}_{i} - \frac{1}{2} \sum_{i \neq j} \mathbf{r}_{ij} \mathbf{v}_{ij} \mathbf{F}_{ij} > \mathbf{n} \longrightarrow \mathbf{q} \cdot \mathbf{n}$$

Or using mesoscopic route using constitutive relations.

#### **Buffer**

![](_page_12_Figure_1.jpeg)

B=buffer (overlap domain) serves to impose fluxes into the particle region.

## **Flux-exchange coupling**

![](_page_13_Figure_1.jpeg)

Buffer is a mass and momentum reservoir for the MD domain. It is used to impose the external momentum into MD via  $\mathbf{F}^{ext} = \sum_{i \in B} \mathbf{F}_i^{ext}$ . Flux at H:  $\mathbf{J}_H^{\phi} = (\mathbf{J}_C^{\phi} + \mathbf{J}_P^{\phi})/2$ .

## **Boundary conditions: CFD->MD**

Fluxes are imposed onto MD across the hybrid interface H:

Momentum:

$$\mathbf{J}_{p} \cdot \mathbf{n} A \Delta t = \sum_{i \in B} F_{i}^{ext} \Delta t + \sum_{i'} \Delta(m_{i'} \mathbf{v}_{i'})$$

![](_page_14_Picture_4.jpeg)

$$\mathbf{J}_{e} \cdot \mathbf{n} A \Delta t = \sum_{i \in B} F_{i}^{ext} \mathbf{v}_{i} \Delta t + \sum_{i'} \Delta \epsilon_{i'}$$

External Force (for momentum);  $g(x_i) = 1$ :

$$\begin{split} \mathbf{F}_{i}^{ext} &= g(x_{i})\mathbf{F}^{ext} / \sum_{i \in B} g(x_{i}) = \frac{A}{N_{B}} \left( \mathbf{J}_{p} \cdot \mathbf{n} - \frac{\sum_{i'} \Delta(m_{i'} \mathbf{v}_{i'})}{A \Delta t} \right) \\ & \text{Flekkoy, Delgado Buscalioni, Coveney, Phys. Rev. E 72, 026703 (2005).} \end{split}$$

#### **Velocity of inserted particles**

Choices:

No additional momentum:

$$\mathbf{v}_{i'}=0$$

Average velocity of inserted particles is equal to continuum fluid velocity:

$$\langle \mathbf{v} \rangle = \mathbf{u}$$

The distribution is for example Maxwellian:

$$\left(\frac{1}{2}\pi mk_BT\right)^{3/2}\exp\left(-m(\mathbf{v}-\mathbf{u})^2/2mk_BT\right)$$

![](_page_15_Picture_8.jpeg)

#### **Insertion/deletion of molecules**

Controlling the number  $N_B$  of molecules in B:

$$\Delta N_B = (\Delta t / \tau_r) (\langle N_B \rangle - N_B)$$

 $\tau_r \sim O(100)$  MD time steps.

- Delete a molecule if  $\Delta N_B < 0$  or when molecule leaves the buffer-end.
- Insert a molecule if  $\Delta N_B > 0$  using USHER- Newton-Raphson-like search method on the potential energy surface. A new molecule is inserted at potential energy  $E_T$ .

$$\mathbf{r}_{cm}^{n+1} = \mathbf{r}_{cm}^n + \frac{\mathbf{F}_{cm}^n}{|\mathbf{F}_{cm}^n|} \delta r$$

$$\mathbf{r}^{n+1} = \mathcal{R}^n_{\delta heta}\mathbf{r}^n$$

Delgado Buscalioni et.al.: J. Chem. Phys 119, 978 (2003), J. Chem. Phys. 121, 12139 (2004).—

## **Triple-scale model**

![](_page_17_Picture_1.jpeg)

- to allow for insertion of larger molecule into a dense liquid
- to allow for grand canonical MD simulation of open molecular systems

R. Delgado Buscalioni, K. Kremer, M. Praprotnik, J. Chem. Phys. 128, 114110 (2008).R. Delgado Buscalioni, K. Kremer, M. Praprotnik, arXiv:0908.0397v1 [cond-mat.soft]

# **Time coupling**

![](_page_18_Figure_1.jpeg)

coupling time:

$$\Delta t_C = n_{CFD} \Delta t = n_{MD} \delta t$$

MD decorrelation time:

 $\tau_c \sim 100 fs$  $\Delta t = 2\tau_c$ 

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R. Delgado Buscalioni, G. De Fabritiis, Phys. Rev. E 76, 036709 (2007).

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# **State variable coupling**

![](_page_19_Figure_1.jpeg)

In the overlap region both descriptions are valid. However, overlap particles are not part of the system- they serve for communication between the two regimes.

# **Constraint dynamics method**

To impose momentum continuity (Couette flow) the total momentum of the overlapping particles is relaxed to the corresponding continuum fluid element momentum using constraint:

$$\sum_{i=1}^{N} p_i - Mu = 0$$

*N* is the total number of particles,  $p_i$  is the momentum of particle *i*, *u*, and *M* are the velocity and mass of the fluid element, respectively. To terminate the extent of the MD region  $F^{ext} = -\alpha p \rho^{-2/3}$  is added to the outer overlap particles.

$$v_{i} = \frac{p_{i}}{m} + \xi \left[ \frac{M}{Nm} u - \frac{1}{N} \sum_{i=1}^{N} \frac{p_{i}}{m} \right]$$
$$\frac{\partial p_{i}}{\partial t} = -\frac{\partial U_{12-6}}{\partial x}$$

S. T. O'Connell, P. A. Thompson, Phys. Rev. E 52, R5792 (1995)

# **Schwartz alternating method**

- Solution of one of the domains provides boundary conditions to the other domain (through the overlap domain) and vice versa.
- This procedure is iterated until both solutions in the overlap domain are matched.
- Requirement: transport conditions of MD and continuum domains must match in the overlap domain.
- Mass transfer across the *H* is controlled using a virtual particle reservoir.

P. L. Lions, In R. Glowinski ed., First International Symposium on Domain Decomposition Methods for Partial Differential Equations, pp. 1-42, SIAM, 1998.

N. G. Hadjiconstantinou, A. T. Patera, Int. J. Mod. Phys. 8, 967 (1997)

## **Effective boundary force+specular wall**

![](_page_22_Figure_1.jpeg)

T. Werder, J. H. Walther, P. Koumoutsakos, J. Comp. Phys. **205**,373 (2005) E. M. Kotsalis, J. H. Walther, P. Koumoutsakos, Phys. Rev. E **76**, 0167709 (2007)

# **Applying pressure to MD domain**

$$p = p_K + p_U = k_B T \rho_n + \rho_n \int_0^{r_c} F_m(r) dr$$

$$F_m(r_w) = -2\pi\rho_n \int_{z=r_w}^{r_c} \int_{x=0}^{\sqrt{r_c^2 - z^2}} g(r) \frac{\partial U_{12-6}(r)}{\partial r} \frac{z}{r} x \, dx \, dz$$

$$r = \sqrt{x^2 - z^2}$$

T. Werder, J. H. Walther, P. Koumoutsakos, J. Comp. Phys. **205**,373 (2005) E. M. Kotsalis, J. H. Walther, P. Koumoutsakos, Phys. Rev. E **76**, 0167709 (2007)

# **Reducing density oscillations**

$$\rho_{i}^{t} \stackrel{e_{i}}{\longrightarrow} CONTROLLER \quad \Delta F_{i} \quad MD \quad \rho_{i}^{m}$$

$$e(r_{w}) = \rho^{t} - \rho^{m}(r_{w})$$

$$\epsilon(r_{w}) = \nabla e(r_{w}) = -\nabla \rho^{m}(r_{w})$$

$$\Delta F_{i}' = K_{p}\epsilon_{i}$$

 $F_i^{new} = F_i^{old} + \Delta F_i = F_i^{old} + 0.25\Delta F_{i-1}' + 0.5\Delta F_i' + 0.25\Delta F_{i+1}'$ 

$$E = \sqrt{\frac{1}{N} \sum_{i=1}^{N} e_i^2}$$

E. M. Kotsalis, J. H. Walther, P. Koumoutsakos, Phys. Rev. E 76, 0167709 (2007)

# **Other hybrid models**

Using Lattice Boltzmann to solve incompressible Navier Stokes equations:

A. Dupuis, E. M. Kotsalis, P. Koumoutsakos, Phys. Rev. E **75**, 046704 (2007).

Total simulation domain is modeled using a continuum solver, where MD computations enter as a local refinement:

W. Ren, W. E, J. Comp. Phys. **204**, 1 (2005) S. Yasuda, R. Yamamoto:, Phys. Fluids **20**, 113101 (2008).

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